

New Robotic Telescope

Date: 28/09/2023

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Universidad de Oviedo

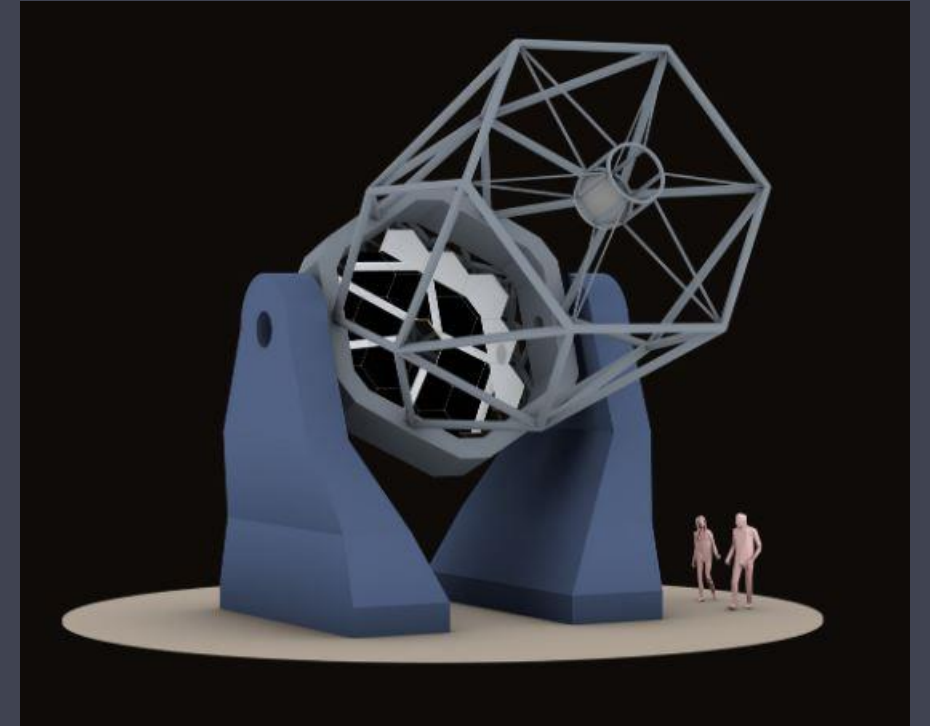
TRACKING
amn.It.com Sfp: Science Fold Position now 'Port 3'
amn.It.com Sfp: Science Fold Position now 'Port 3'
amn.It.com Sfp: Science Fold Position demand 'Port 6'
amn.It.com Sfp: Science Fold Position now 'Port 6'
amn.It.com Sfp: Science Fold Position demand 'Port 6'
cas.It.com Amc: New movement state entered: HALTING_AXIS
alt.It.com Amc: New movement state entered: HALTING_AXIS
azm.It.com Amc: New movement state entered: HALTING_AXIS
cas.It.com Nsc: Changing user reported state from TRACKING to STOPPING
alt.It.com Nsc: Changing user reported state from TRACKING to STOPPING
azm.It.com Nsc: Changing user reported state from TRACKING to STOPPING
cas.It.com Amc: New movement state entered: AXIS_HALTED
azm.It.com Amc: New movement state entered: AXIS_HALTED
alt.It.com Amc: New movement state entered: AXIS_HALTED
cas.It.com Nsc: Changing user reported state from STOPPING to IDLE
alt.It.com Nsc: Changing user reported state from STOPPING to IDLE
azm.It.com Nsc: Changing user reported state from STOPPING to IDLE
azm.It.com Amc: New movement state entered: TRACKING
alt.It.com Amc: New movement state entered: TRACKING
alt.It.com Nsc: Changing user reported state from IDLE to TRACKING
azm.It.com Nsc: Changing user reported state from IDLE to TRACKING
cas.It.com Amc: New movement state entered: TRACKING
cas.It.com Nsc: Changing user reported state from IDLE to TRACKING
azm.It.com Amc: New movement state entered: TRACKING



NEW ROBOTIC TELESCOPE



- International collaboration to build the largest (\varnothing 4 m) entirely robotic telescope in the world
- Quick response (on target in 30 s)
- Sited at ORM in La Palma
- Based on the success of the LT and GTC
- Standard for future telescopes





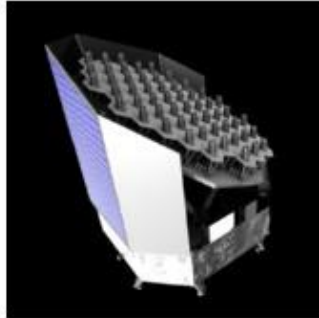
NEW ROBOTIC TELESCOPE



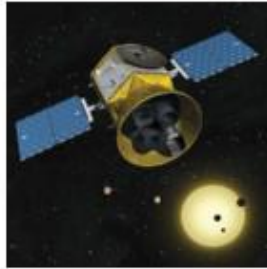
- A 4 m aperture diameter, robotic mode
- A Ritchey–Chretien design (f/2 prime focus, f/10 total)
- Fast slewing requirement, i. e. lightweight structure (~60 TM)
- Rapid response (30 sec on target)
- FoV ~ 5'-30' diameter at Cassegrain focus
- Full optical and near IR ranges
- Focal stations at direct and folded Cassegrain.
- Image elongation no greater than 0.2" in ten minutes
- Optimal image quality dominated by seeing (median ~0.7" in La Palma)



NEW ROBOTIC TELESCOPE



PLATO: launch 2026



TESS: launch 2018



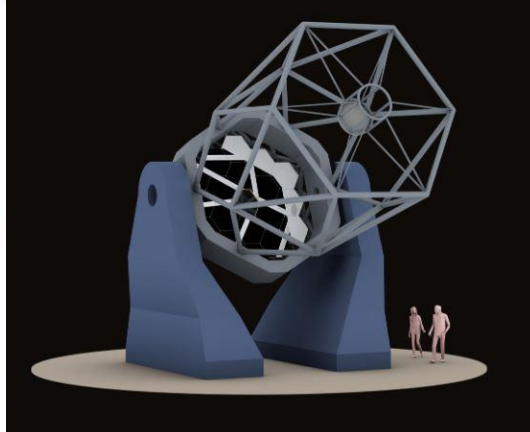
SVOM: launch 2024



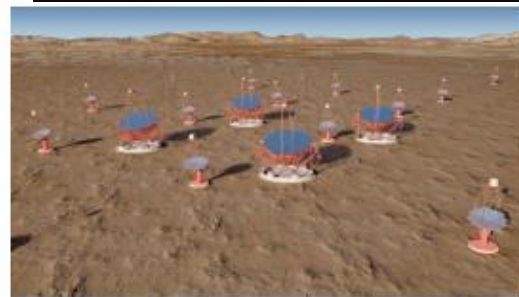
Gaia DR2 2018 DR3 2021



ALIGO/aVirgo full sensitivity 2022



CTA completed ~2023



SKA phase 1 completed 2020

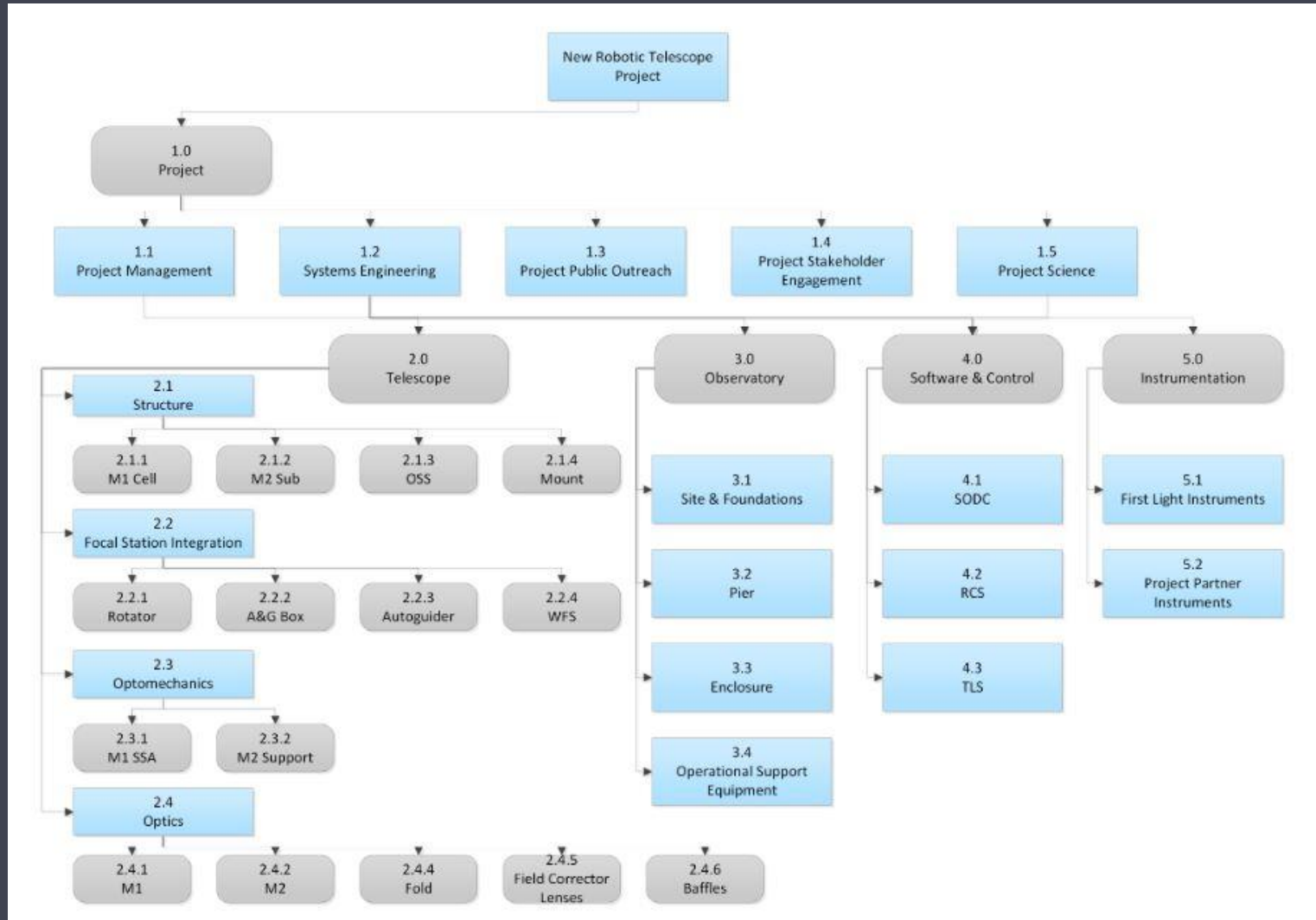
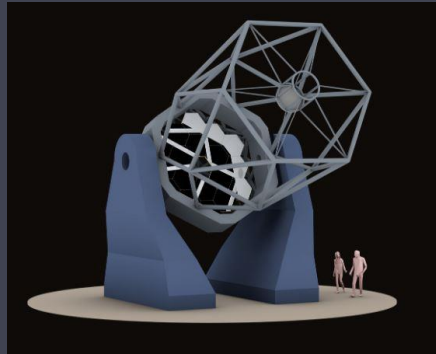


LSST: science first light 2021





NEW ROBOTIC TELESCOPE





TEC
Centros

TEC
tecnología

TEC
espaciales

TEC
NRT
Nuevo
Telescopio
Robótico

TEC

TEC

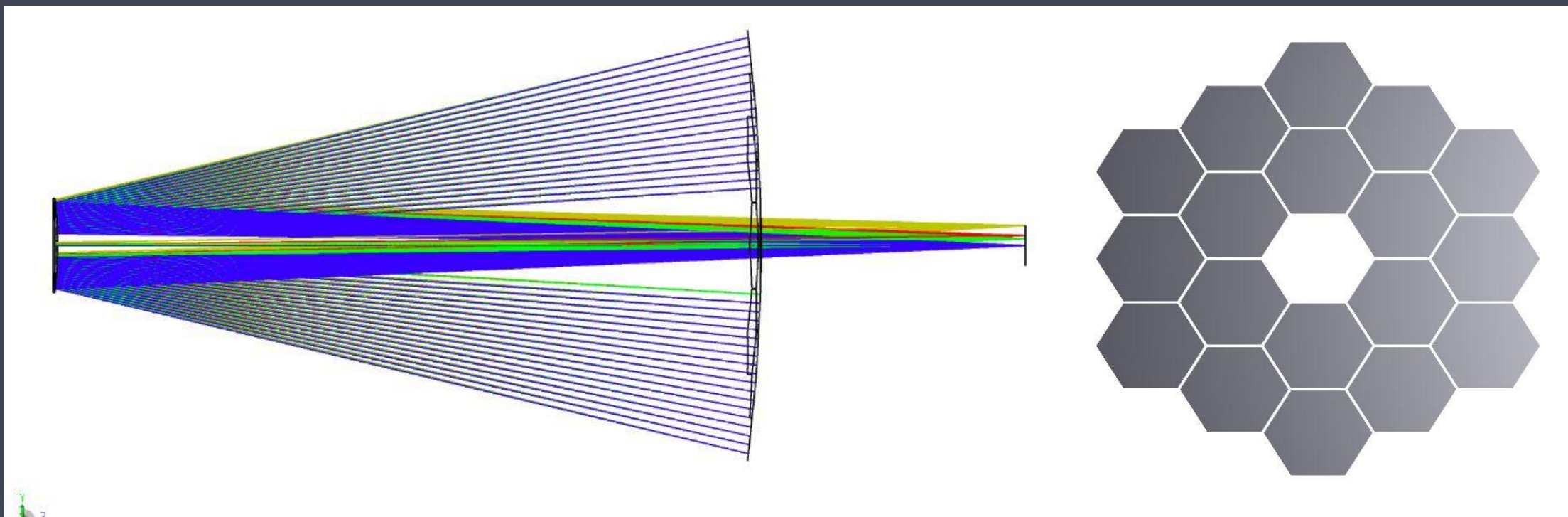
IACTEC





NEW ROBOTIC TELESCOPE: OPTICS

- A 4 m primary monolithic mirror ~5,500 kg.
- That can be largely reduced by constructing it out of hexagonal segments (the segments can be much thinner).



HEX-18 possibility to produce them at IAC; optomechanics similar to GTC

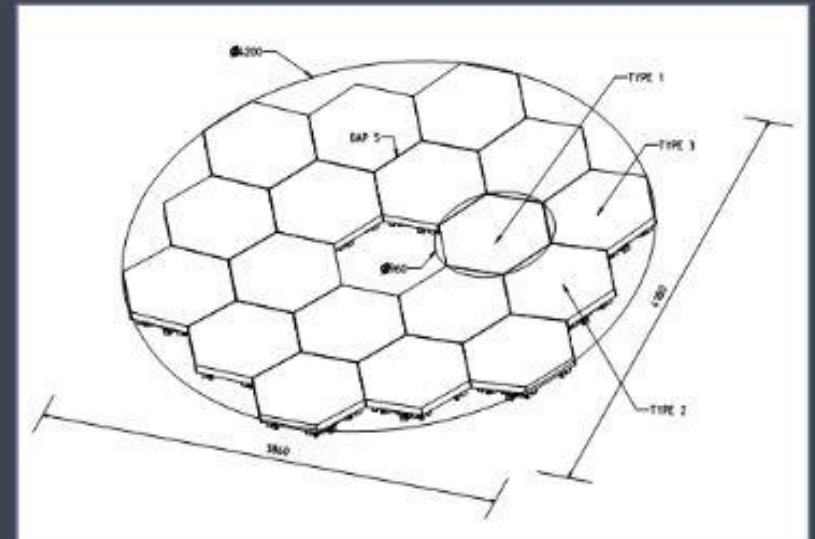


NEW ROBOTIC TELESCOPE: OPTICS

	Distance (mm)	Radius (mm) (edge)	RoC (mm)	Conic
M1	-6657.69	2090	-16770	-1.020449
M2	6657.69	455.3 (465.3)	-4257.7	-2.331897
BFD	1650	264.7		
Fold mirror	850	190 (200)		
Focal plane		194.6		



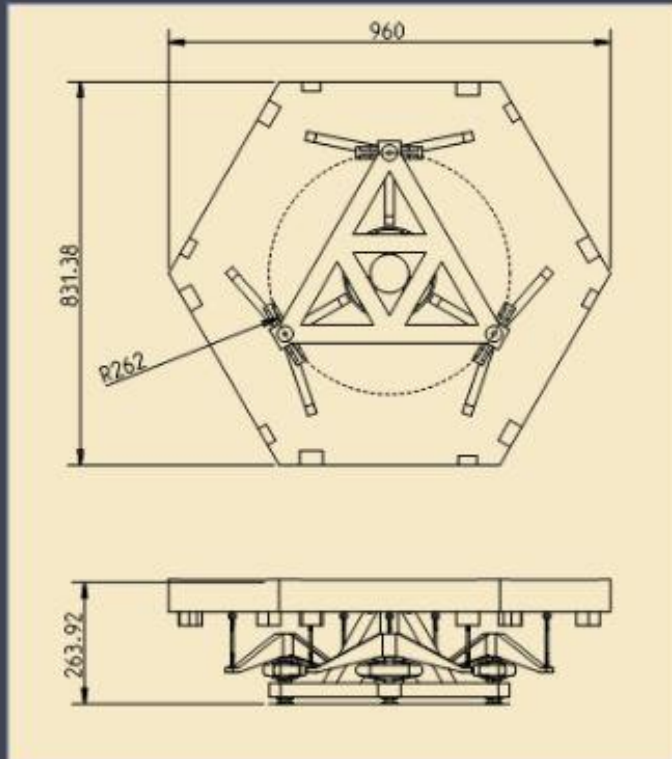
- Richey-Chretien optical configuration
 - f/10.635
 - Plate scale 220 μ m/arcsec
- \varnothing 4.18m, 18 segment primary mirror
 - Segment adjustment - Tip, tilt, piston
- Multiple instruments at Cassegrain focal station
 - 1x Straight Through Instrument
 - 6 x Folded Port Instruments
- Back Focal Distance (BFD) of 2.5m
- Cassegrain focal station field of view
 - 30 arcmin - straight through port
 - 14 arcmin - folded ports



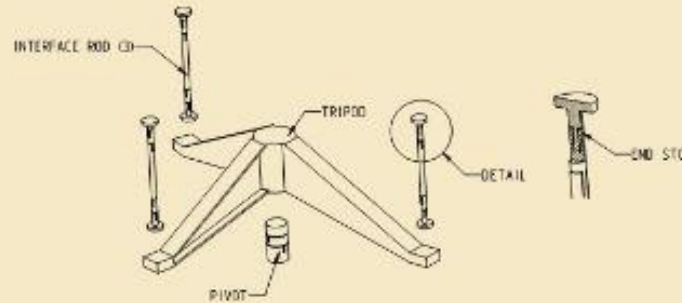


NEW ROBOTIC TELESCOPE: M1

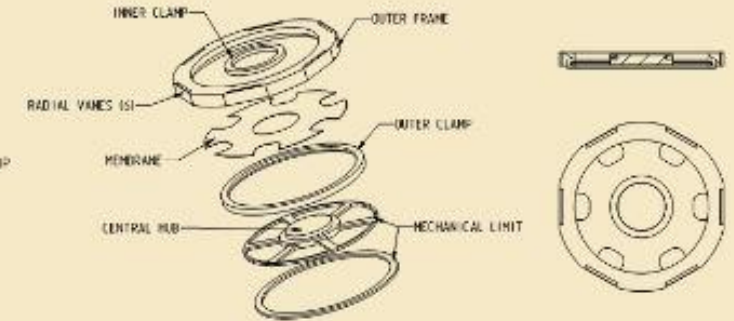
- Segment support design
 - 9 points axial Whiffle Tree
 - 3 tripods
 - Membrane based lateral support
 - 120Kg per segment assembly



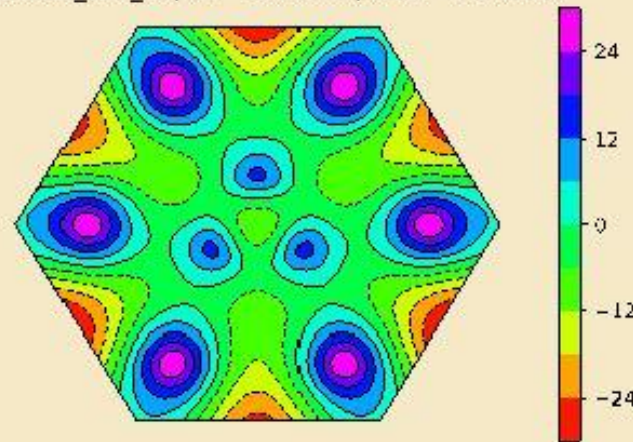
Axial support



Lateral support



s_bstrate_tets_G7, PV - 63.1 nm, RMS - 11.4 nm

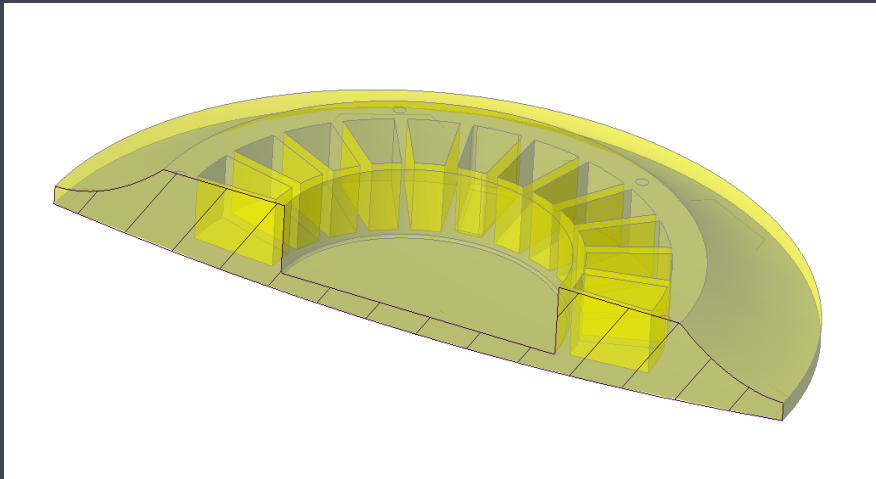


Subcell

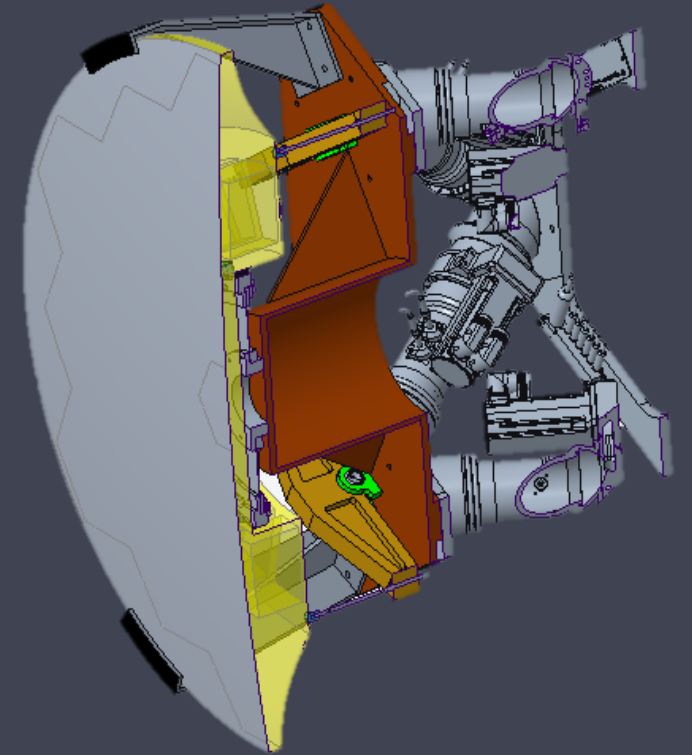




NEW ROBOTIC TELESCOPE: M2

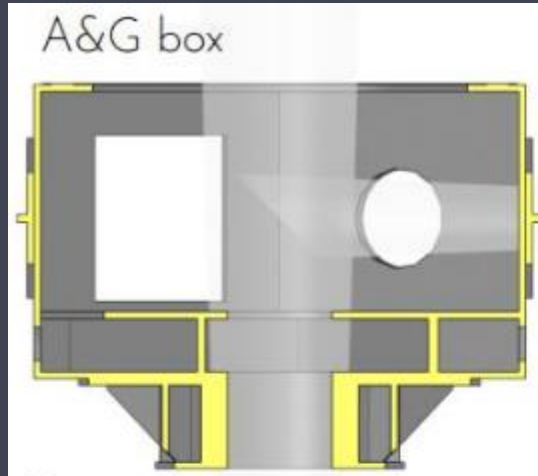


- Lightweight substrate
- 6 points axial support
- Membrane lateral support
- Hexapod for focus and corrections in tilt and decentre
- 250Kg assembly mass (incl hexapod)



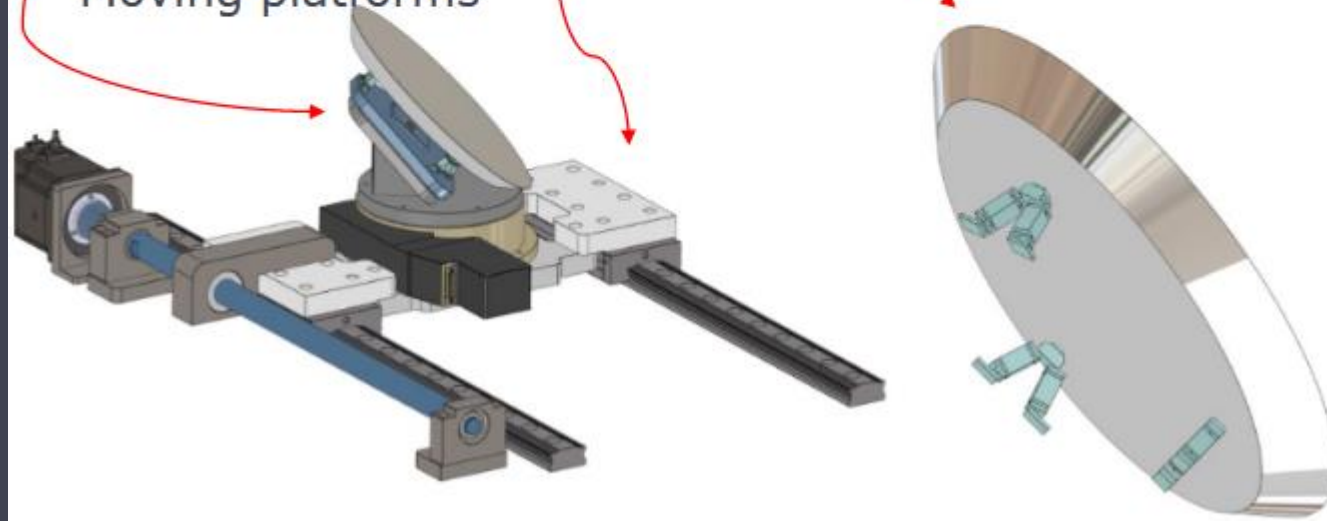
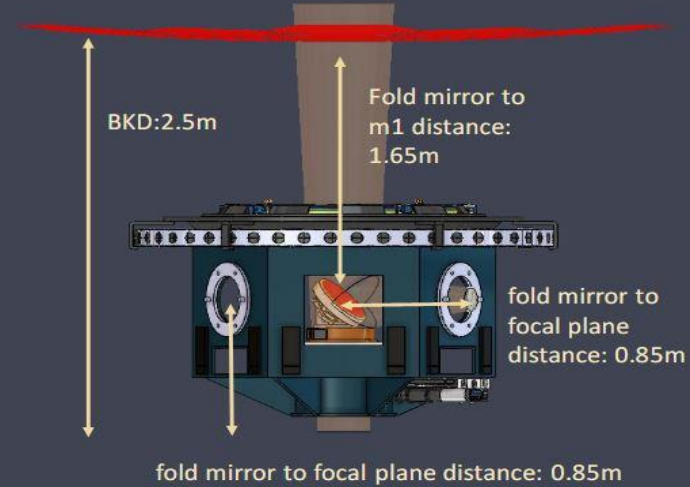


NEW ROBOTIC TELESCOPE: focal stations



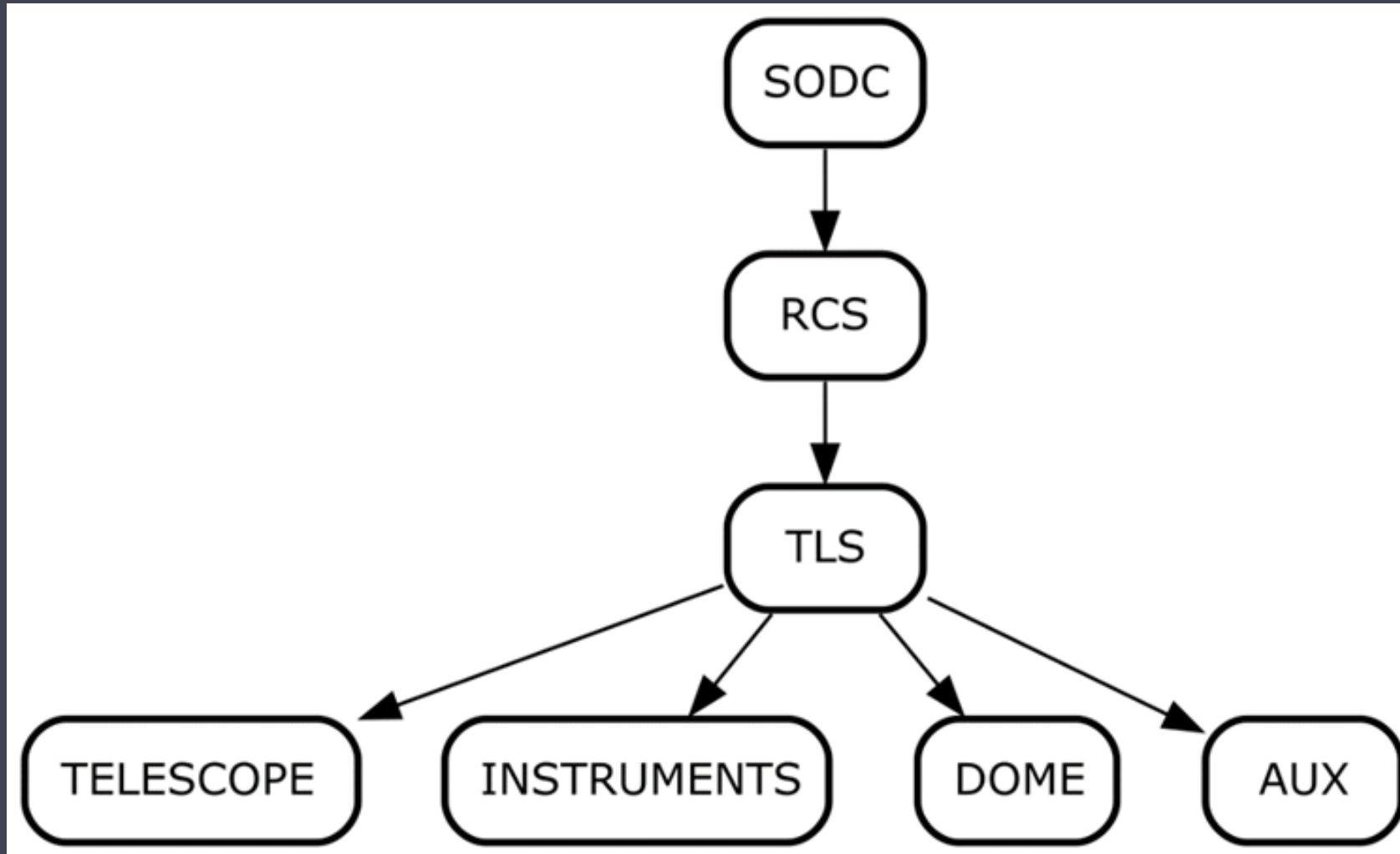
Scope

- Fold mirror
- Opto-mechanic support
- Moving platforms





NEW ROBOTIC TELESCOPE: CONTROL SYSTEM





NEW ROBOTIC TELESCOPE: STRUCTURE

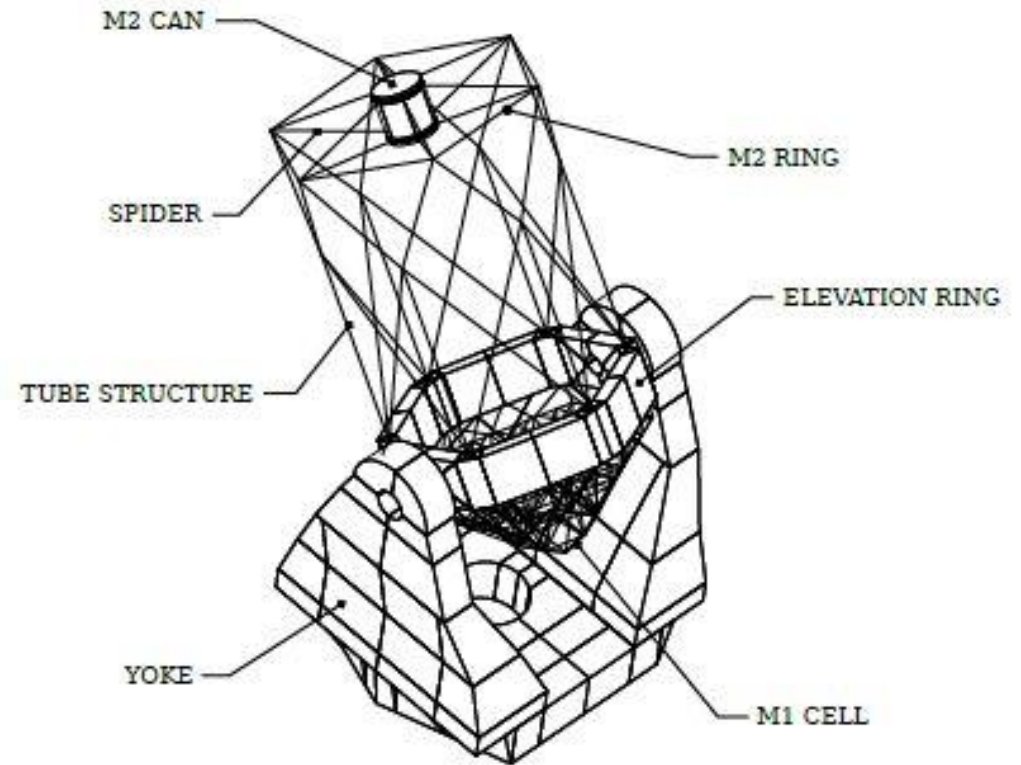
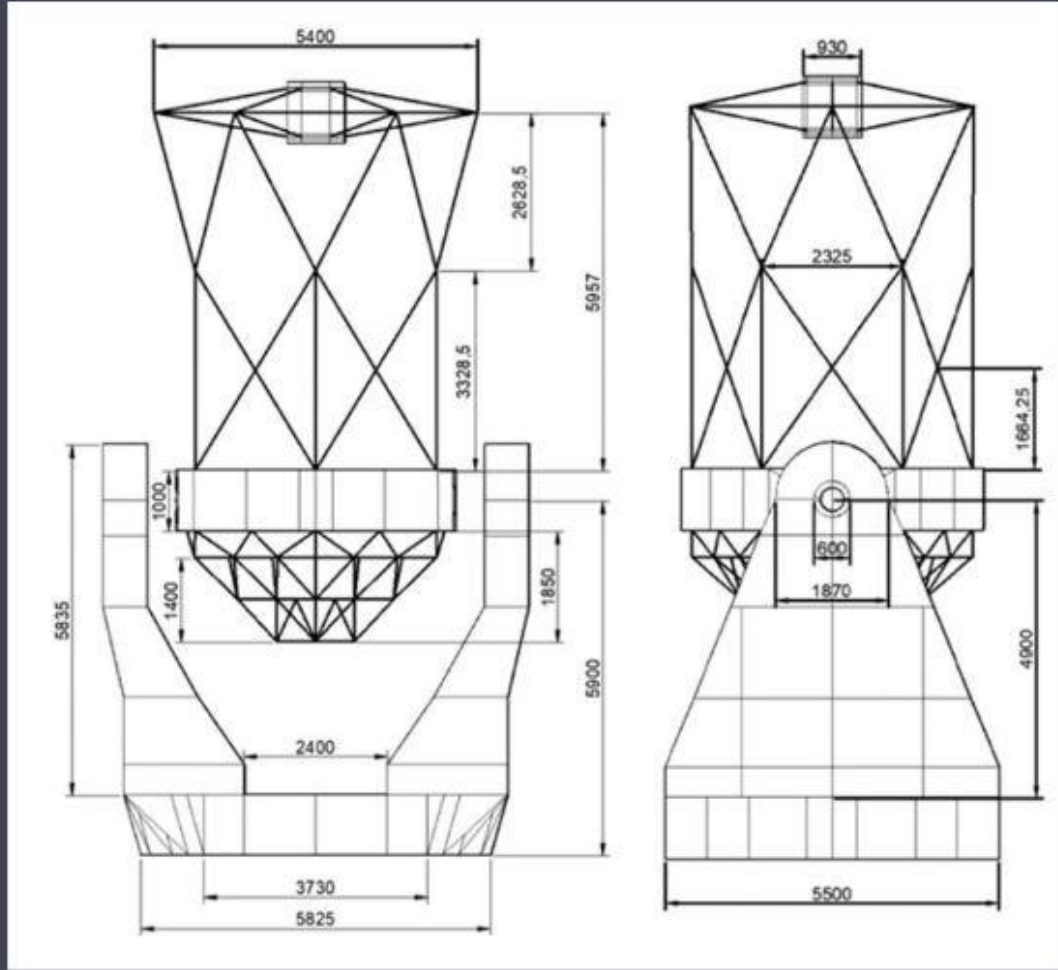


Fig. 2.5 NRT main structure overview.



NEW ROBOTIC TELESCOPE: STRUCTURE



High level

- Range of motion ($\pm 270^\circ$ for azimuth axis and $20-90^\circ$ for elevation axis)
- Fast time to target (< 30 s) with 5 arcsec RMS blind pointing accuracy
- Provide a clear optical path with low obscuration while maintaining alignment

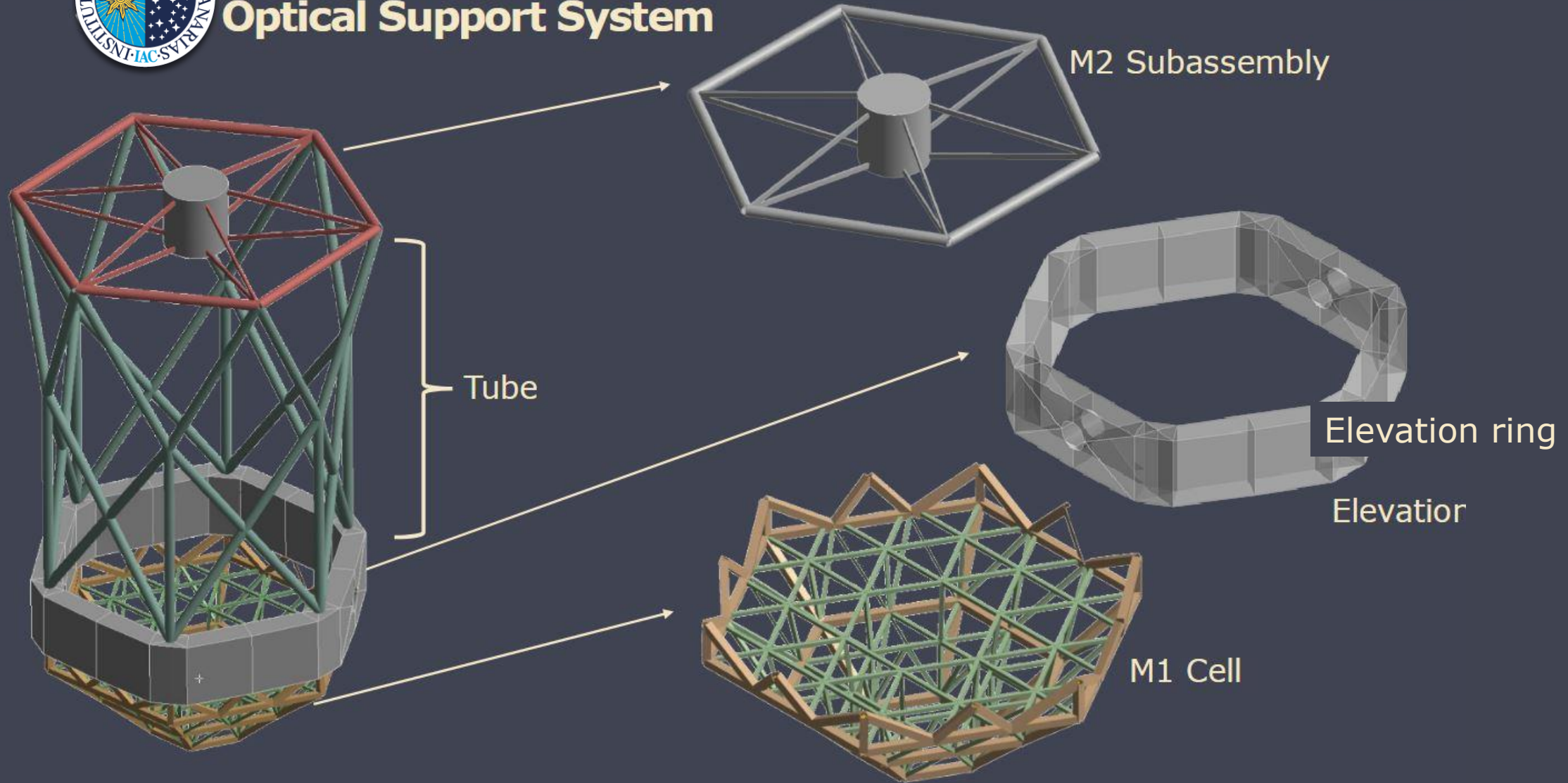
Key metrics

- Locked Rotor Frequency ≥ 10 Hz as a target
- M1 – M2 decentre $< 2-3$ mm
- M1 – M2 piston $< 2-3$ mm
- M1 – M2 tip-tilt $< 1-2$ arcmin

NEW ROBOTIC TELESCOPE

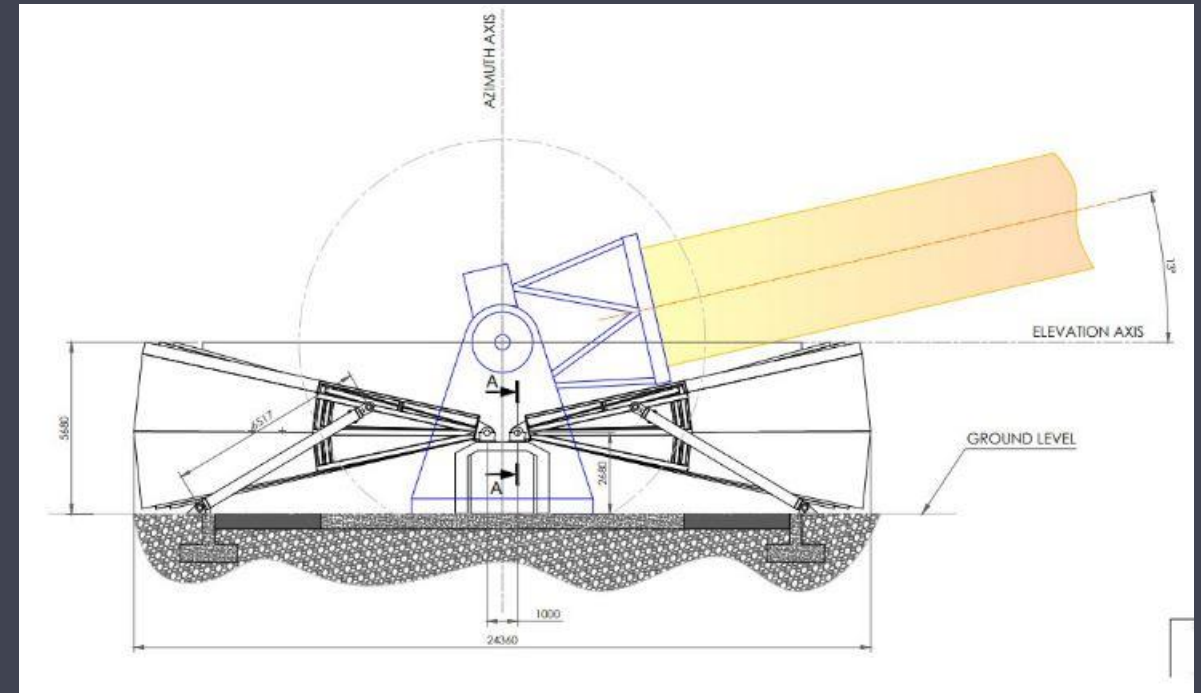
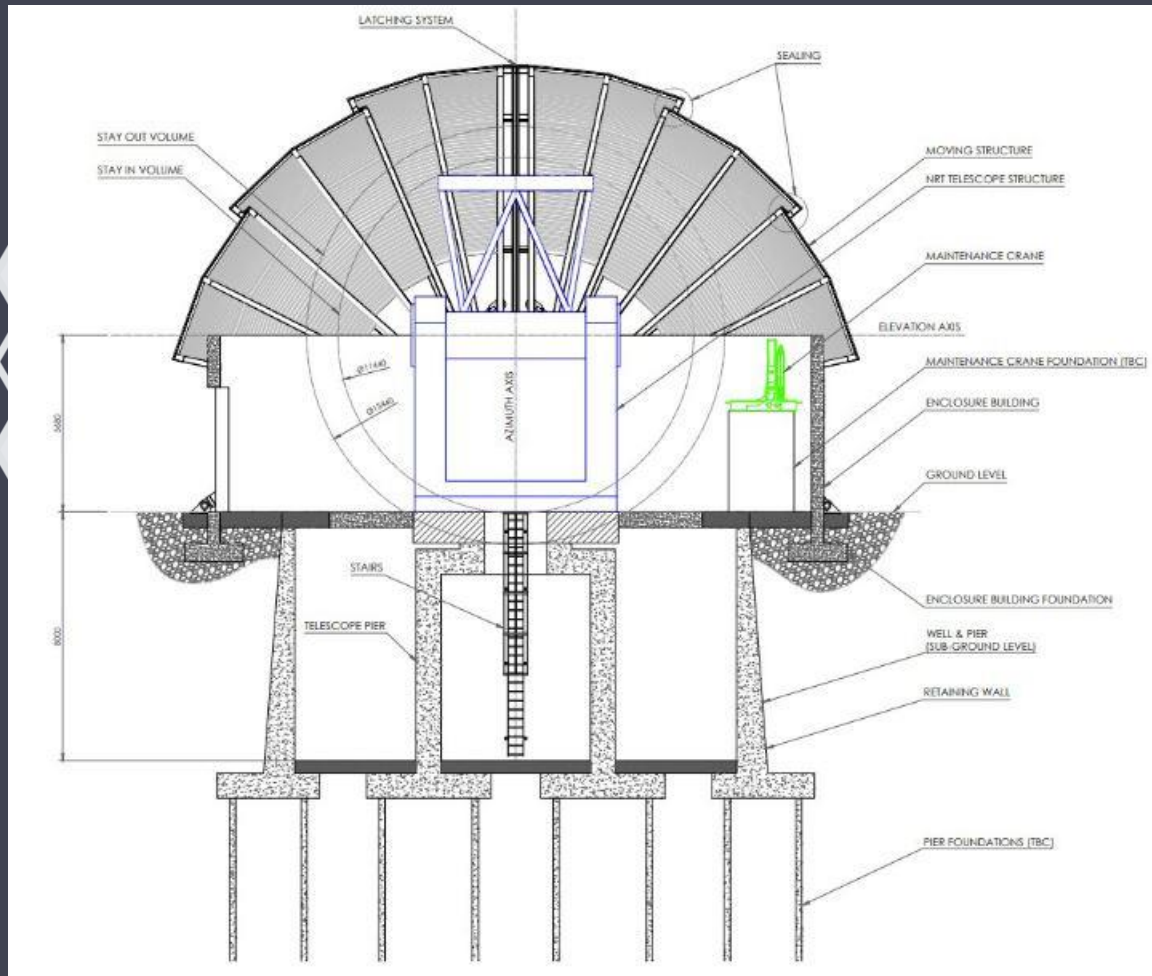


Optical Support System



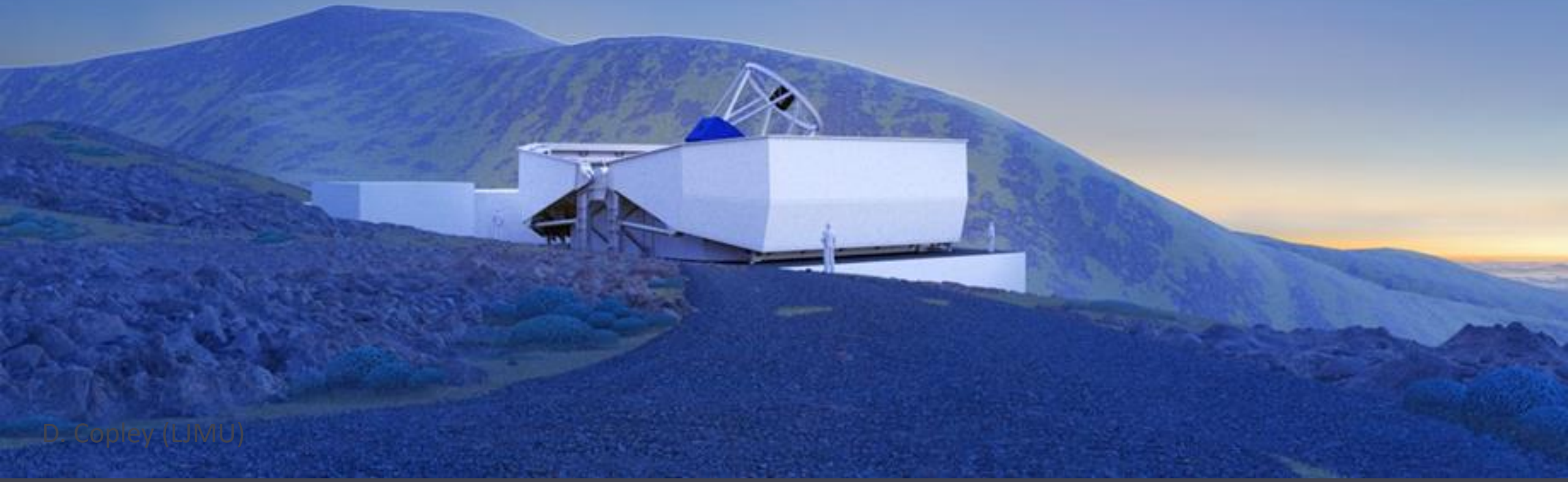


NEW ROBOTIC TELESCOPE : ENCLOSURE





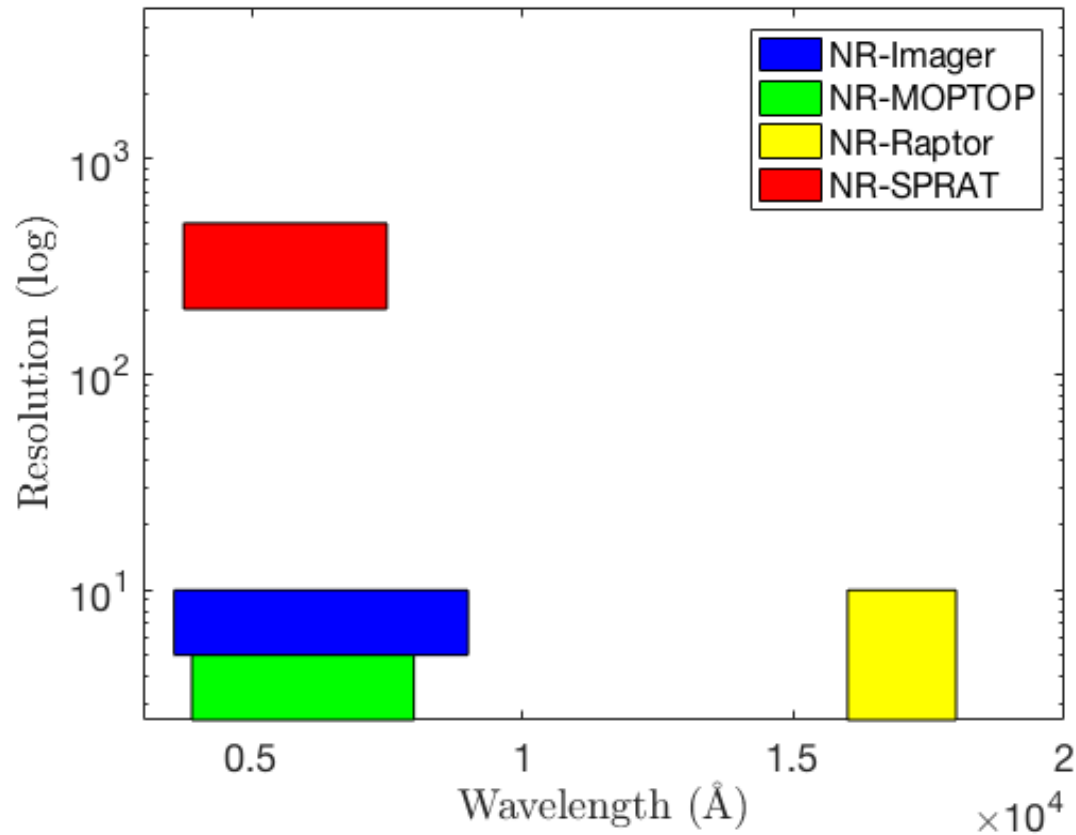
NEW ROBOTIC TELESCOPE: ENCLOSURE



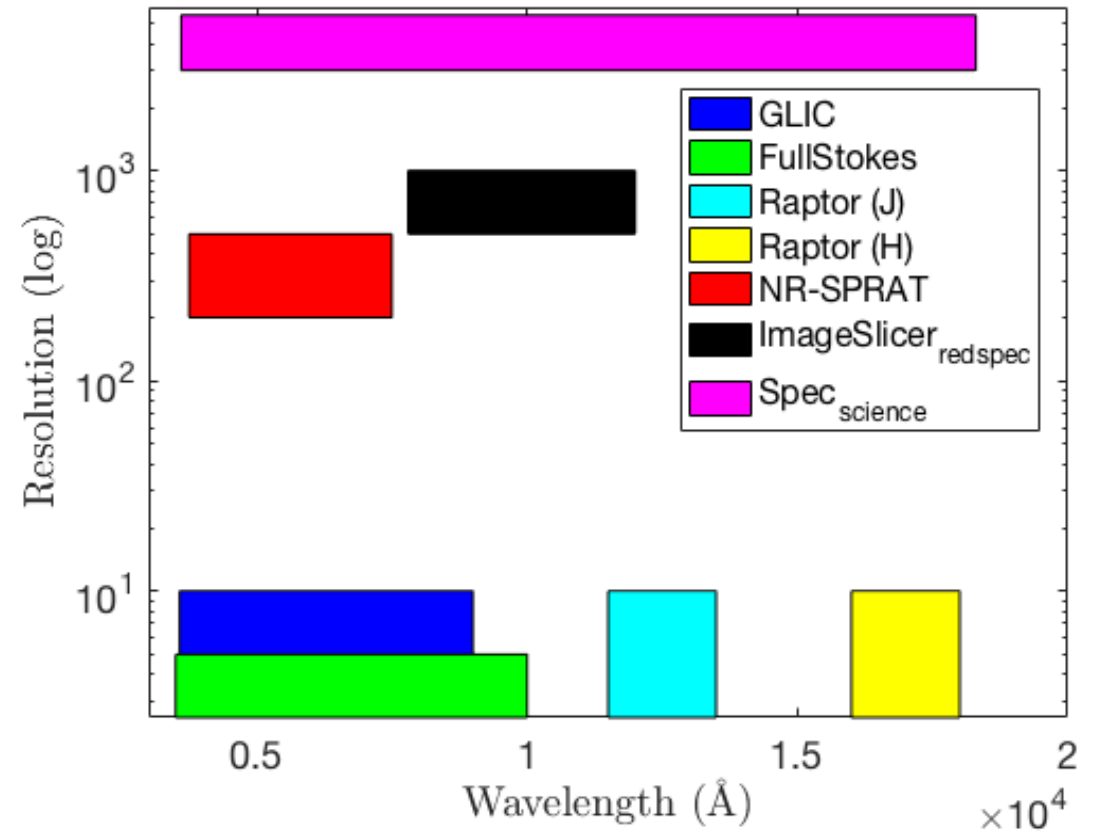


NEW ROBOTIC TELESCOPE: instruments

First Light Instrumentation

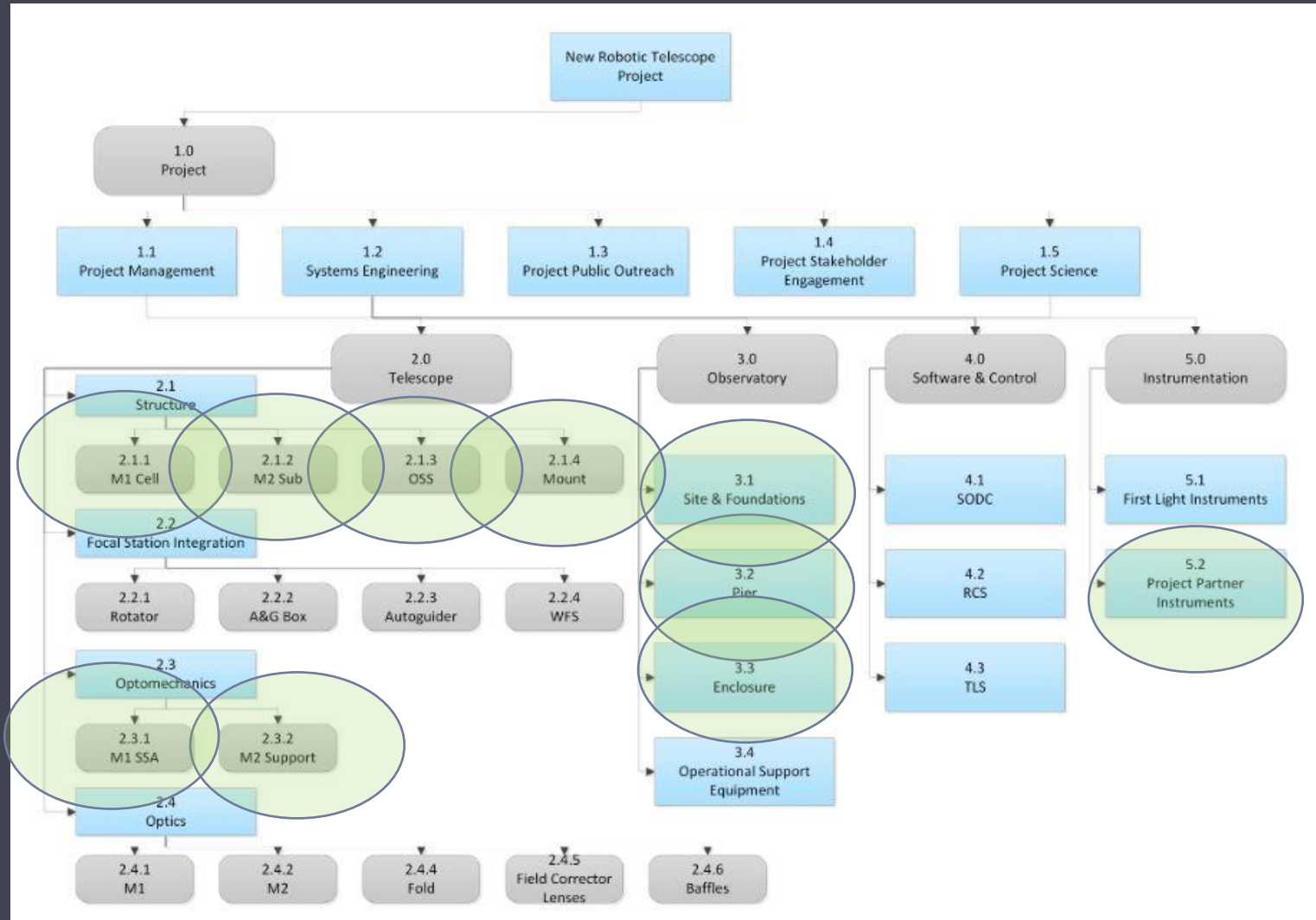


Second Generation Instrumentation





NEW ROBOTIC TELESCOPE



NRT timeline



2018 – 2020

- Funding.
- Conceptual design.

2021 – 2024

- Complete consortium.
- Preliminary design.
- Detailed design.

2024 – 2026

- Construction of the telescope and first light instrumentation.

2026 – 2027

- Integration, first light and commissioning.



SUMMARY



1. Key astronomical facility (power: \varnothing 4 m and quick response: 30 s) for time domain astronomy.
2. Semented apertura formed by 18 hexagons (~1 m each)
3. Sited at ORM with superb atmospheric conditions.
4. Standard for a future generation of large robotic telescopes.
5. Trigger of CSOA.