

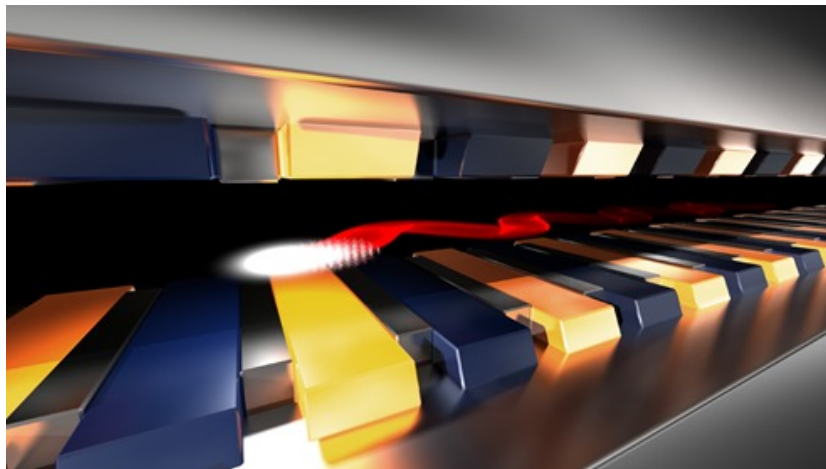
# Instrument and Data Systems Control at European XFEL



6<sup>th</sup> October 2022,

Steve Aplin

Department Head Data at European XFEL



**Big Science  
Business  
Forum  
2022**



2016

2017

2018

2019

2020

2021

2022

CONSTRUCTION

COMMISSIONING

EARLY OPERATION



# Estimates for procurement related to beamline control systems 2022 - 2027

■ Control system integration from external vendors and software consultants	250 kEuro / year
■ PLC System assemblies	150 kEuro / year
■ PLC System parts	100 kEuro / year
■ Cabling and connectors	100 kEuro / year
■ MicroTCA Systems and cards	100 kEuro / year
■ <b>Total Estimated Expenditure 700 kEuro / year</b>	

# We need more Data ! ... be careful what you wish for ...

Detectors Overview

Monica Turcato, Detector Group, 32<sup>nd</sup> DAC meeting, May 30<sup>th</sup>, '21

Gotthard-II

2

## Detectors for EuXFEL

X-ray energy

Hard X-rays  
6-25 keV

Soft X-rays  
0.5-3 keV



Noise: 50 e- (HG)  
Dyn range: 100 8 keV ph

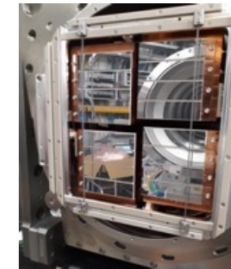
ePix100 (MID, HED)



Jungfrau x 17 (all hard X-ray inst.)

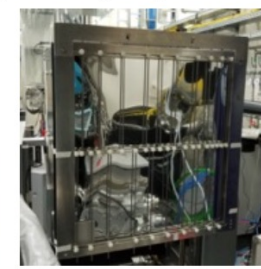
Noise: 80 e- (HG)  
Dyn range: 10<sup>4</sup> 12 keV ph

AGIPD (SPB/SFX, MID)



Noise: 350 e- (HG)  
Dyn range: 10<sup>4</sup> 12 keV ph

LPD (FXE)



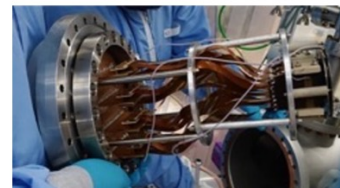
Noise: 2010 e- (HG)  
Dyn range: 10<sup>5</sup> 12 keV ph

pnCCD (SQS)



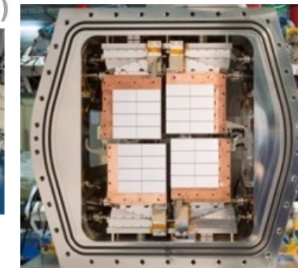
Noise: 3 e-  
Dyn range: 1500-3000 1 keV ph

MCP + DLD (SQS, 2x SCS)



Single ph. sensitivity down to few hundred eV  
Up to 50-60 ph/pulse

DSSC (SCS, SQS)



Noise: 60 e-  
Dyn range:  
N x 256 ph @ 4.5 MHz –  
N x 512 @ f ≤ 2.2 MHz  
N ≤ 1 for single ph sens.

10 Hz

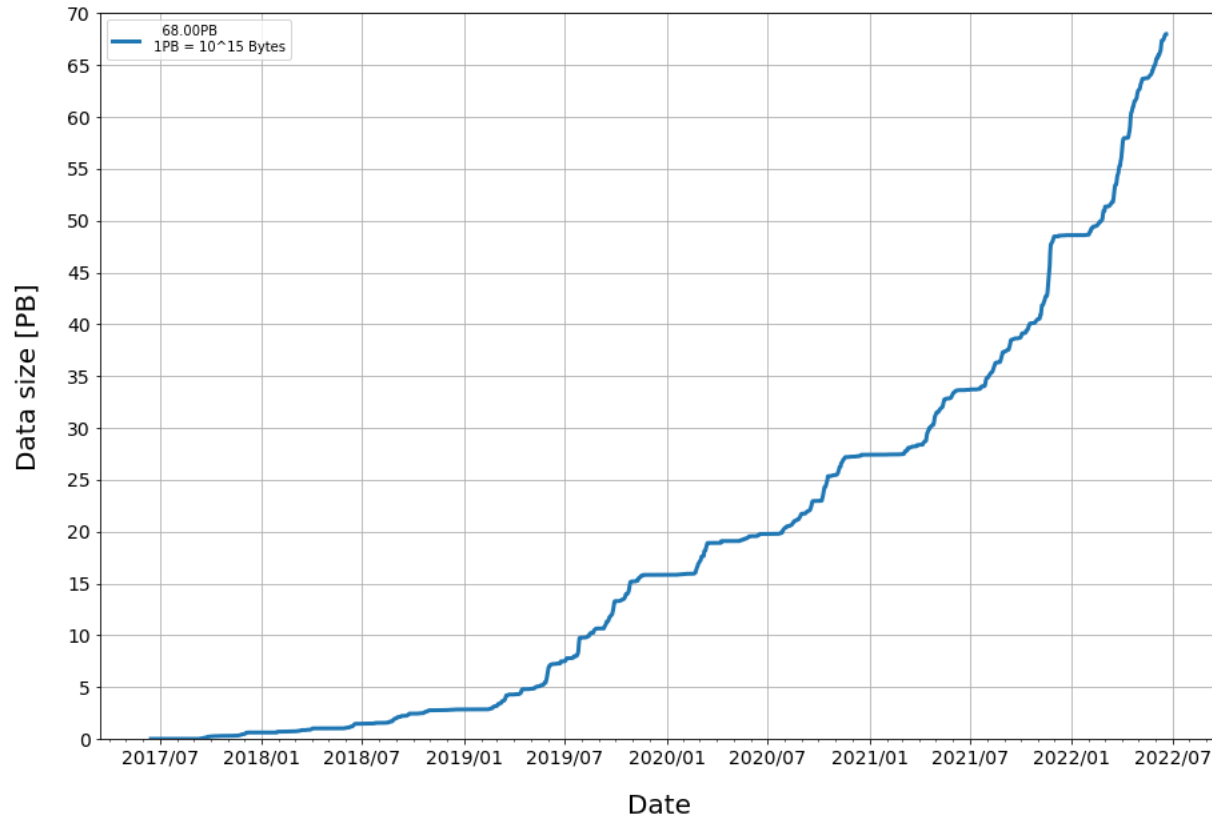
4.5 MHz

Rate

European XFEL

# We need more Data ! ... be careful what you wish for ...

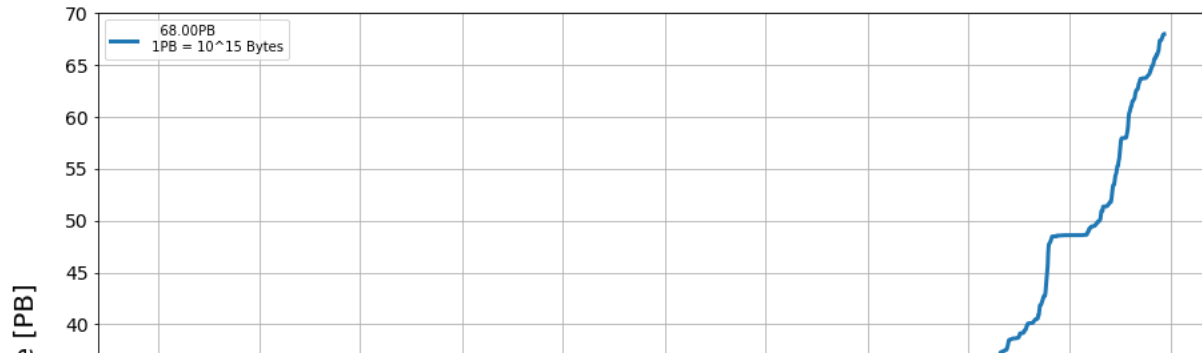
Raw Data Generated at European XFEL Instruments



Detector type	Data/sec
AGIPD 1Mpxl	~7 GB/s
AGIPD 1Mpxl Double images	~14 GB/s
AGIPD 4Mpxl	~30 GB/s *
LPD 1Mpxl	~10 GB/s
DSSC 1Mpxl	~16 GB/s

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Raw Data Generated at European XFEL Instruments



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The data flow from all four experiments at LHC for Run 2 was anticipated to be about *25 GB/s after* data reduction

- ALICE: 4 GB/s (Pb-Pb running)
- ATLAS: 800 MB/s – 1 GB/s
- CMS: 600 MB/s
- LHCb: 750 MB/s

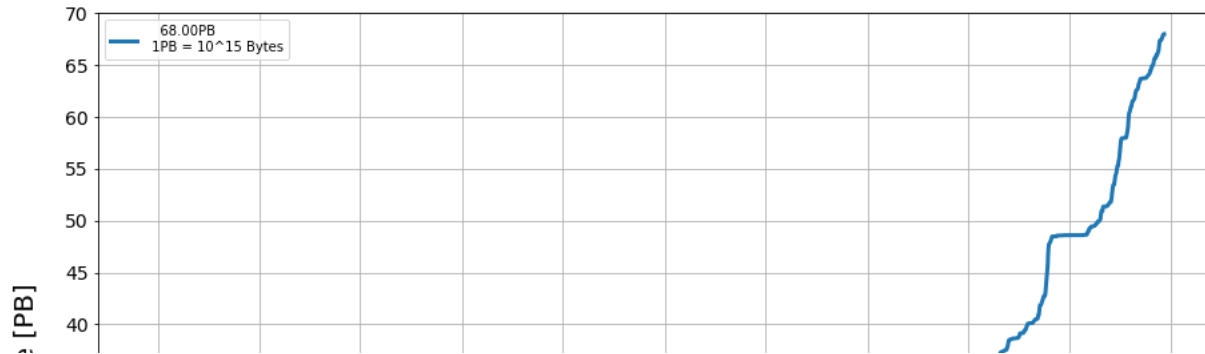


Data reduction in particle physics is built into it's DNA, it is intrinsic to the field's experimental viability.

The experiments are designed from the ground up on data reduction.

# We need more Data ! ... be careful what you wish for ...

Raw Data Generated at European XFEL Instruments



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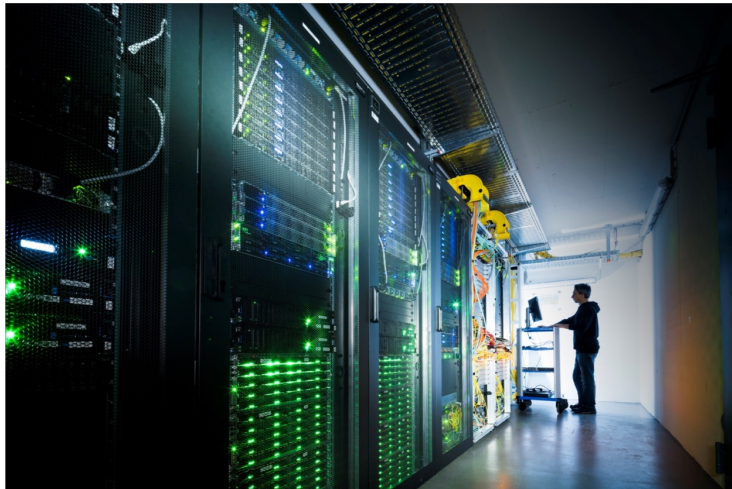


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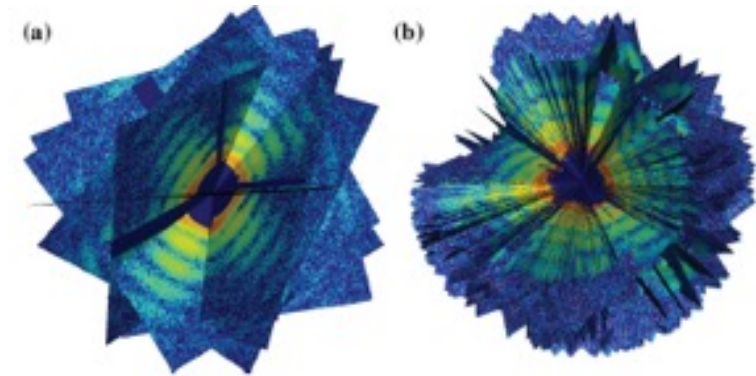
**Required Ingest Rate of Data  
Center  
100 GB/s**

# Data Reduction and Compression is the only hope ...

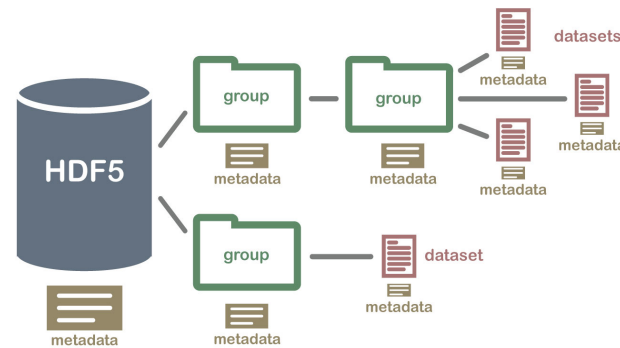
## Reduce to Store



## Reduce to Process



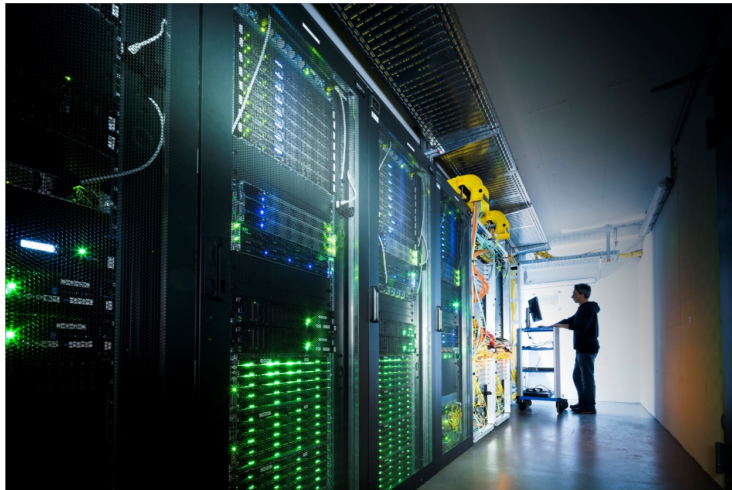
## Reduce to Transport



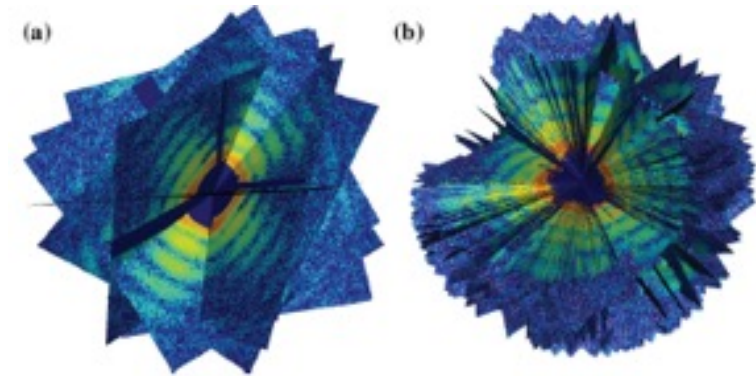


# Data Reduction and Compression is the only hope ...

## Reduce to Store



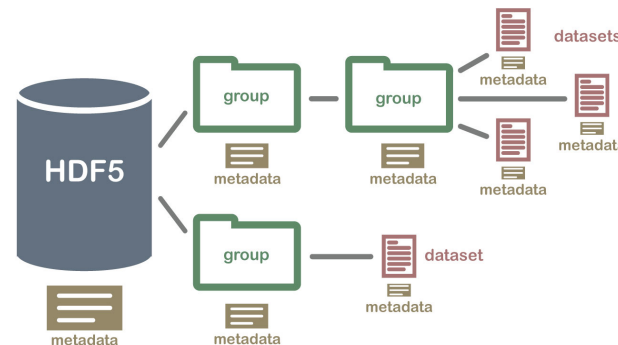
## Reduce to Process



## Reduce to Transport

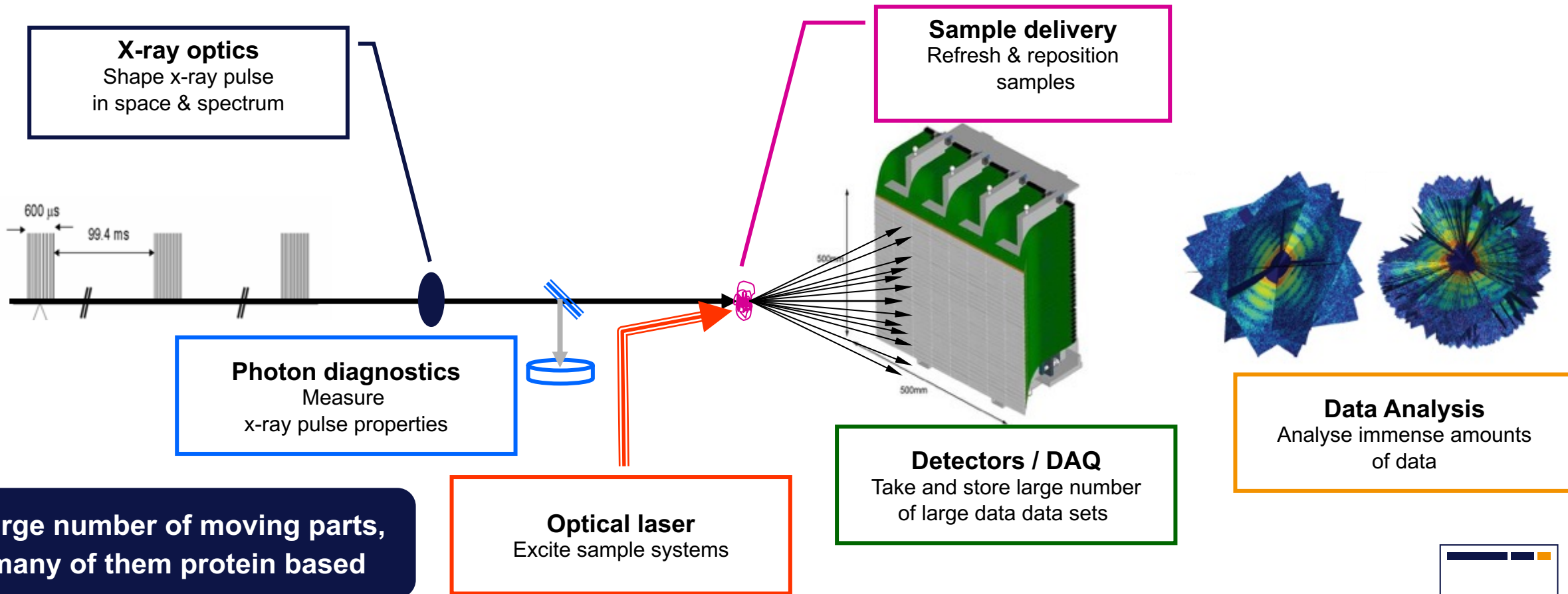


Energy price increase means the Storage : I/O : CPU balance will need to be rethought

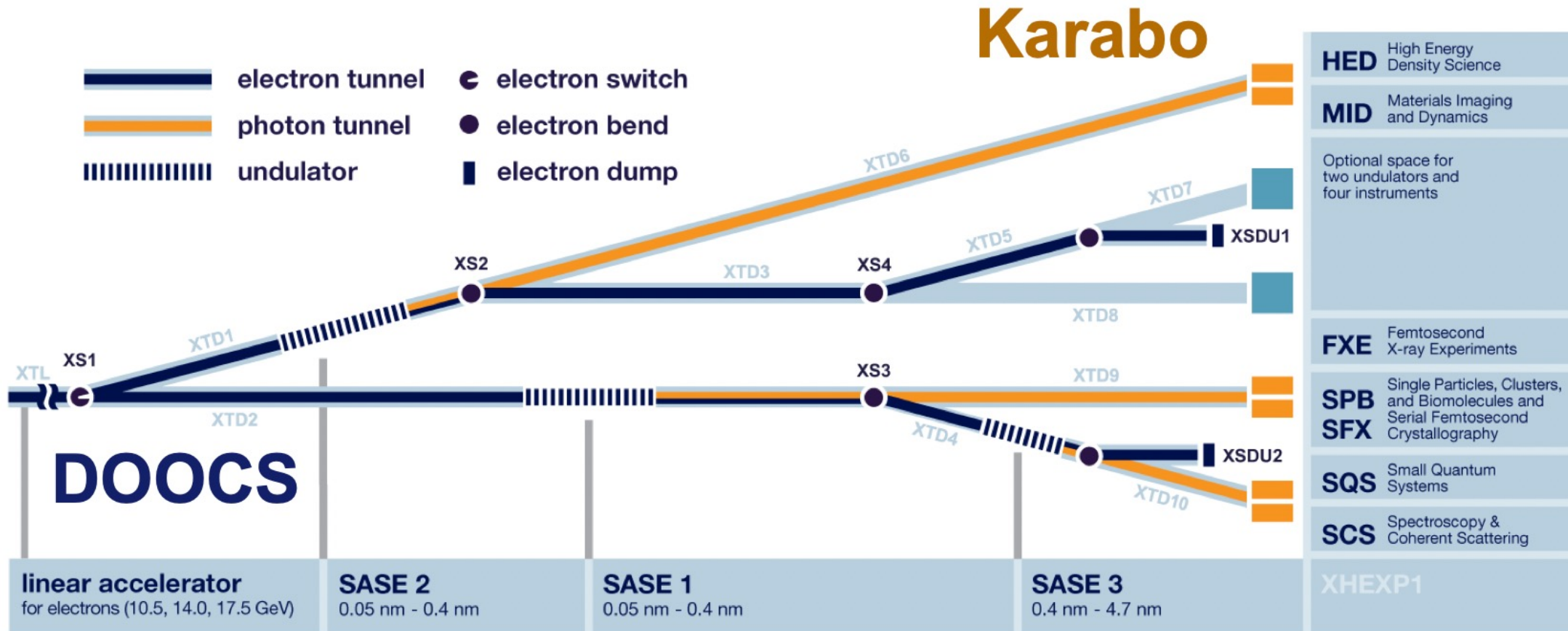


# Maturing Systems 7 PB in 7 days 17<sup>th</sup> Nov. to 23<sup>rd</sup> Nov.

## Controls – Hardware and Software

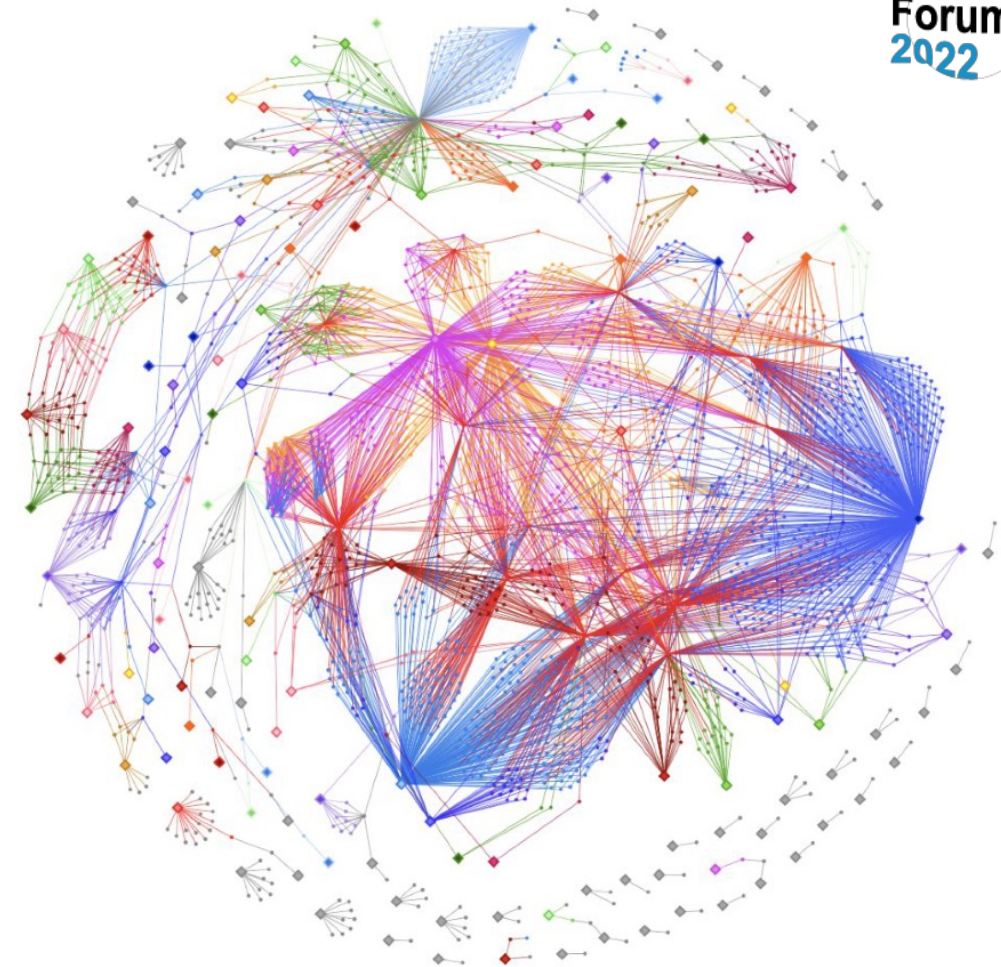


# Beamlines and experimental stations



# Karabo SCADA System

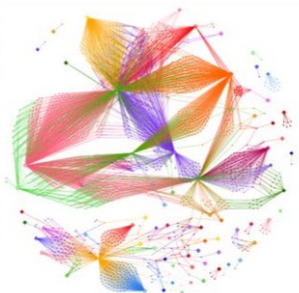
- Karabo is the main control system for the photon tunnels and instruments of the European XFEL
  - Broker-based, event-driven architecture
  - TCP connections for large data
  - GUI with integrated panel/scene builder
  - Python & C++ APIs
  - Functionality added as self-descriptive plugins, so called devices
- Karabo has matured in 4 years of operation
  - 20k devices, 2M properties
  - Routinely handles data rates of 20GB/s
  - **Soon: public release, MPL2.0 license**



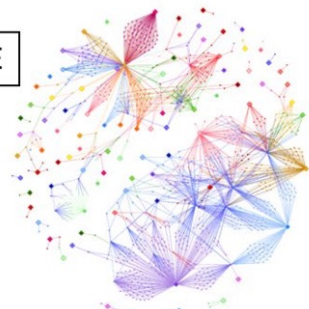
The MID instrument in Karabo

# Karabo Eco System

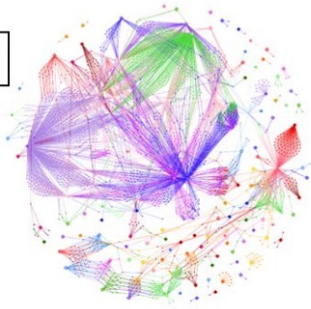
SA1



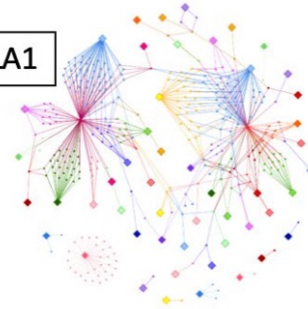
FXE



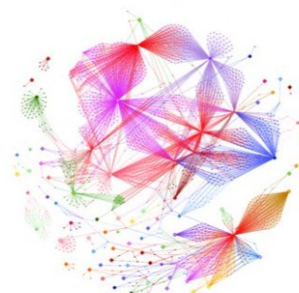
SPB



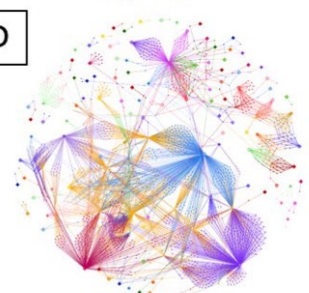
LA1



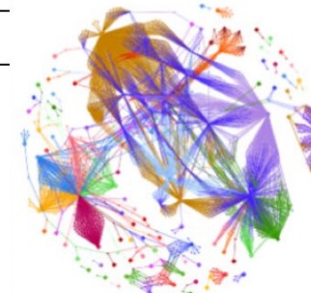
SA2



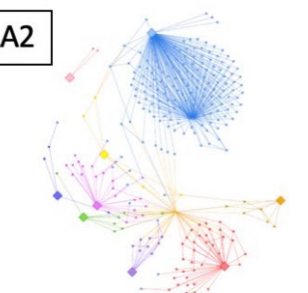
MID



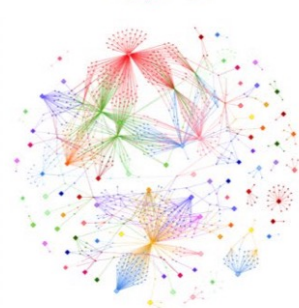
HED



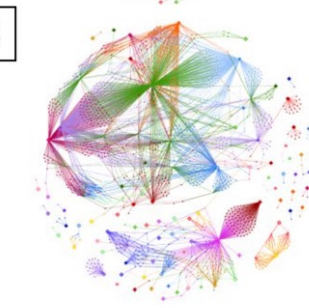
LA2



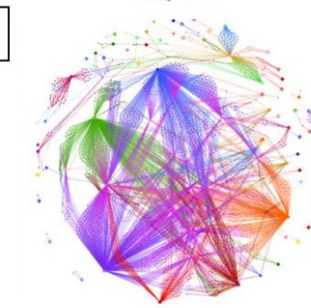
SA3



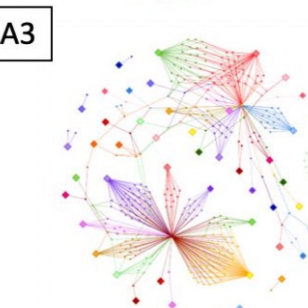
SCS



SQS



LA3



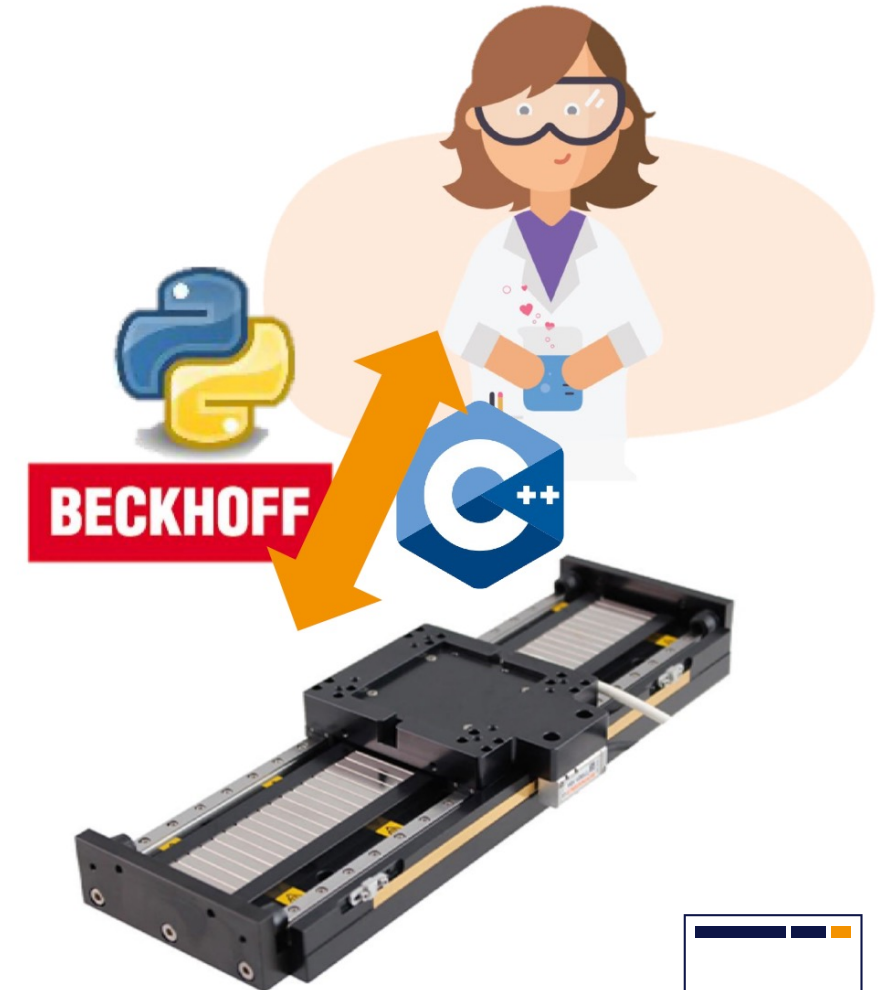
# properties # devices

topic

topic	# properties	# devices
LA1	26914.0	257.0
LA2	28103.0	250.0
LA3	32013.0	298.0
SA1	192656.0	1588.0
SA2	274426.0	2260.0
SA3	233216.0	1886.0
FXE	121905.0	905.0
HED	268688.0	1892.0
MID	258094.0	1789.0
SCS	205557.0	1444.0
SPB	267424.0	1872.0
SQS	306817.0	1954.0

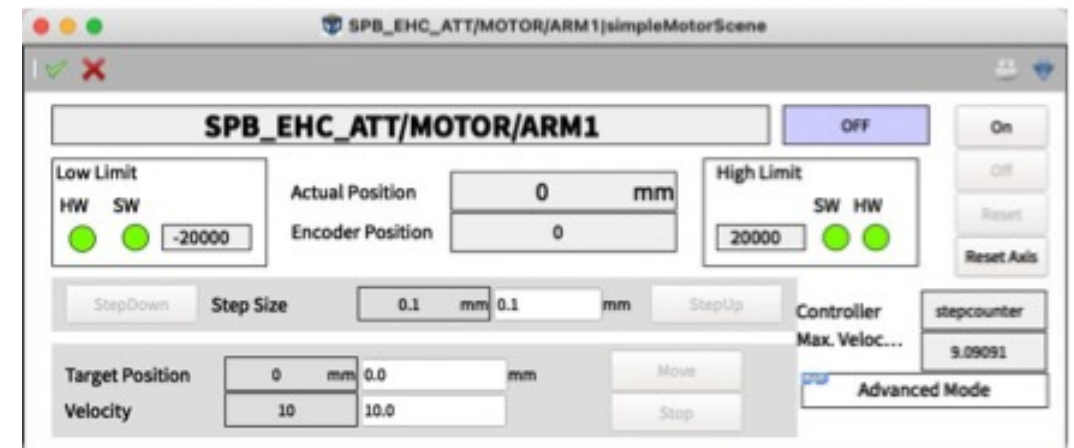
# Higher Level Motion Control in Karabo

- Generally, two types of integration:
  - Hardware integration through Beckhoff PLCs → Control system interfaces through tcp protocol to in-house developed PLC firmware
  - Direct integration in Karabo → Control system uses vendor-protocols and/or drivers
  - In both cases Karabo provides the operator (and often also commissioning/configuration) interface
- Additionally, Karabo control system provides
  - High-level procedures and virtual/software motors/axes
  - Scanning functionality
  - Sync functionality to other components



## Integration via Beckhoff: Karabo (mainly) provides the Interface

- EEE group implements most functions in firmware on Beckhoff PLCs, so-called “soft devices”
  - Logic & state machine
  - Parameters
- Two generic flavours:
  - MC2: uses Beckhoff motion library
  - SimpleMotor: deprecated custom-made
- PLC and Karabo interact via custom TCP protocol
- PLC provides self-description of functionality
  - Karabo Beckhoff package render this as interface
  - Adds state protection
  - Possibly some higher level functions



**Generic operator interface for an MC2 motor**

## FPGA based online calibration and hit-finding project by Maxeler

- The Development phase will officially end soon
  - Calibration and Peak finding hardware algorithms have been implemented in the platform
  - Validation and integration of the platform in XFEL is ongoing
- Contribution from multiple XFEL colleagues
  - Control, Data Analysis, Detector, ITDM and SPB
  - Amount of time/expertise needed was underestimated
- Goal is to have the platform up and running in SPB as soon as validation is concluded
  - Press release or possible article in a Conference will follow





# FPGA based online calibration and hit-finding project by Maxeler

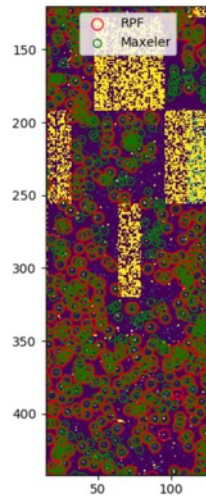
**Start of project**

- Installation of platform in Laboratory
- AGIPD Reference Data
- Initial Maxeler Software models



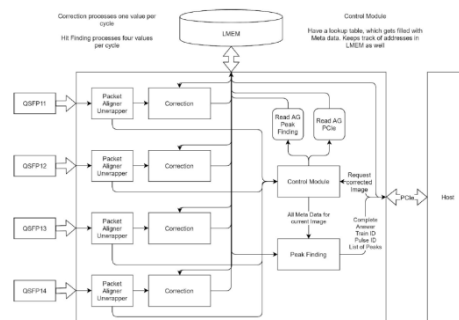
**Deliverable 1**

- Validation of Maxeler SW results
- Data handling in the Maxeler platform
- Software library interface



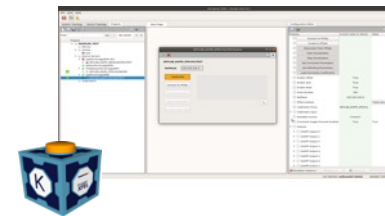
**Deliverable 2**

- FPGA implementation of Software models
- Decoding of XTDF/TTP data protocol
- Extra development for calibration algorithm



**Deliverable 3**

- Validation of Maxeler XTDF/TTP decoding
- Extra extra development for calibration algorithm
- Karabo Interface to the Platform



**Deliverable 4**

- Validation of entire data flow in laboratory
- Installation and Validation of platform in SPB

**End of project**

**We are here now!**

- Karabo device for communication with Calibration database
- Validation of Hardware Calibration